

Publishers' page

Publishers' page

Publishers' page

Publishers' page

Dedication Page

(optional)

Preface

The primary motivation for adaptive memory programming, therefore, is to group and unify all these emerging optimization techniques for enhancement of the computational capabilities that they offer to combinatorial problems which are encountered in real life in the area of production planning and control.

We confront this pitfall technically, by introducing explicit remarks about the generality of results at appropriate places; methodologically, by accumulating enough applications for every major idea to make its validity and generality stand out; and philosophically, observing that physics moves forward most of its ideas by analogies to cleverly chosen simple systems for which profound intuitions have been formed.

Special attention has also been paid to the wave-current interaction problems. Several models are evaluated by comparing the numerical results with laboratory data. It is quite clear that these higher-order modified equations are adequate for modeling the wave propagation from deep water to shallow water. However, to apply these models in the surf zone further study of breaking waves and the proper parameterization of wave breaking processes are essential.

One of most surprising findings is coastal engineering research in the last two decades is the robustness of the shallow-water equation models in calculating the wave runup in swash zone. Although the wave breaking process is usually not considered in the shallow-water equations, with a proper tuning of the numerical dissipation as well as the bottom friction, these models can predict the time history of runup heights for various types of incident waves with impressive accuracy. These models have also been extended to examine the interactions between water waves and coastal structures, which are either impermeable or protected by a layer.

The second order wave theory must be employed to include the effects of wave drift forces and springing since they are caused by the quadratic

nonlinearity. To consider ringing and wave slamming, cubic nonlinearity and higher order nonlinearity must be included in the formulation.

The factors which have contributed most towards this are the growth of the uranium industry, the acceptance of solvent extraction as a process suitable for industrial use on a large scale, the development of techniques of leaching and reduction at temperatures up to 240°C at moderate pressures, and the demand for numerous less-common metals and other elements.

To model wave slamming and ringing as mentioned above and other nonlinear phenomenon, it is necessary to undertake fully nonlinear transient analyses, usually involving numerical time marching. At present many such numerical models exist. One of common difficulties faced by these models is the procedure to track the location of free surface, especially in the case of wave breaking. Different applications associated with each method, especially in wave hydrodynamics are discussed. More than one hundred references are cited in the paper.

T. M. Chan

Contents

Preface	vii
1. The High Quality and Competitive Products of Manufacturing System	
1.1 The Planning	1
1.1.1 The binomial distribution	2
1.1.1.1 The multiple management	3
1.2 Self-Study Discrete Regression	9
2. Genetic Algorithms	13
2.1 Introduction	13
2.1.1 Genetic algorithms versus traditional optimization and search techniques	14
2.2 Fundamentals of Genetic Algorithms	15
2.2.1 Selection	16
2.2.2 Partial bits exchange	17
2.2.2.1 The bits exchange operator	17
2.3 Interior-Outer-Set Model	17
Appendix A The Dynamic Optimization	23
Bibliography	27
<i>Index</i>	31

Chapter 1

The High Quality and Competitive Products of Manufacturing System

The present trend in manufacturing, products have to be delivered at competitive cost, at the required time and in an acceptable quality to the customer. Competitive cost, timely delivery of products and attainment of high quality require proper planning and effective control of work through a manufacturing system.

1.1 The Planning

The planning is complex because it takes into consideration all the various aspects that are necessary in order to achieve the business and strategic plans of a manufacturing firm. Typically, input to a production planning system is in numeric form such as the number of products to be produced or assembled per week. From this, planned order release has to be determined, each job has to be scheduled and work centres have to be loaded. In each stage, a check on capacity is necessary in order to ensure that equipment and workforce are available to meet production target.

This theory was developed based on new challenges of which the enterprises face in the market, such as reverse correlativity, bubbled falsehood, virtual exchange, disorder chaos and unstable variation. The objective of opportunity cybernetics is to achieve the optimal combined profit for the enterprises with multiple venture management through a dynamic modeling control.

The theory of opportunity cybernetics and decision harmonizing in this paper is designated to overcome the difficulties of modern enterprises with multiple venture management. In the following, we will introduce several exceptional phenomena that affect the multiple venture management in the competitive global market. Then, we will outline the basic concepts and modeling of opportunity cybernetics and decision-harmonizing theory. An iterative process is

used to acquire knowledge about the layout, and reorganize the scenegraph structure based on the acquired knowledge, and cell formation within the layout

An additional source of disagreement comes from the analysis of word distributions of a certain length. Monkey languages imply word length follows an exponential distribution given by the invariant state had to correspond to that of a perfect mixture

$$P(L) \propto (1 - q)^L. \quad (1.1)$$

The variations of global economy environment are mostly disordered, such as the prices of stock and futures. However, these variations have two qualitative features: seasonal fluctuation and emergent mutation. Some conclusions can be drawn from the research of disordered phenomena of multiple venture management. Firstly, fluctuation is not always a bad phenomenon. Without fluctuation, the life of management is over and fluctuation contains opportunities for improvement and making profit. Secondly, emergent phenomenon is a turning point for multiple venture management that is an indication of a success or a failure of management.

1.1.1 The binomial distribution

For the binomial distribution, the first and second moments are $n(N) = pN$ and $n^2(N) = Np(1 - p) + N^2 p^2$. Then fluctuation in n for a fixed value of N is given as

$$W(n, N) = \frac{n^2(N) - n(N)^2}{n(N)} = 1 - p; \quad 0 \leq p \leq 1, \quad (1.2)$$

Using the value of W_0 calculated for $[\mathbf{h}_1, \mathbf{h}_2]$ in Eq. (1.2) we obtain the new W_{model} for 1.0 unit $\Delta \mathbf{h}$.

The geometric properties of the Euclidean 3-space are encoded in its *structure preserving transformation group*, namely the *Euclidean group*, which is the semi-direct product of the *translation group* and the *orthogonal group*. The former is isomorphic to the 3-dimensional vector group over \mathbf{R} , and it acts simple-transitively over the Euclidean 3-space.

Thus, the *spherical geometry* is, actually, a part of Euclidean geometry. On the other hand, the whole Euclidean geometry can be regarded as the study of *orthogonal invariants* of the 3-dimensional vector group over \mathbf{R} , which clearly reveals the central geometry. Two spheres of the same radius are obviously congruent to each other while a scaling factor k maps a sphere of radius r to a

sphere of radius kr . Thus, all spheres are “*similar*” to each other (i.e. of the same shape), while their *sizes* are determined by their radii. The increasing order of these parameters is related to the sensitivity of the corresponding market to short term variations and consequently indicates larger risks to the investors.

Example 1.1 The making vector algebra a powerful tool for studying spherical geometry. In this Section, we shall choose such a modern approach to develop the basic theory of spherical geometry. From a global overview of geometry, spherical geometry is, of course, just a part of Euclidean geometry. In view of the fact that spheres are exactly the orbits of the orthogonal groups, spherical geometry studies the part of Euclidean geometry that is *encoded in the orthogonal group*. The quality of the initial solution in terms of closeness to the final solution is dependent on the ability of the algorithm to handle the different types of constraints in the mathematical problem formulation.

Solution The methods we have considered do not take into account any “dynamic” aspect of term structure modeling. We expect that the analysis of equilibrium models could provide a deeper insight also on the cross-sectional estimation problem. This is pretty important since there is already evidence of relevant differences between the predictions of existing models and the experimental data (an example is the volatility term structure).

The common essence for these enterprises is the uncertainty of management outcome. That is the reason why the manager cannot find a long-term and changeless way for fluctuate business environment and management objects. The theory of opportunity cybernetics and decision harmonizing in this paper is designated to overcome the difficulties of modern enterprises with multiple venture management.

1.1.1.1 *The multiple management*

One of the limitations of a 2D block layout is that it is difficult to comprehend the final layout solution. Certain qualitative parameters and functional inadequacies become evident once the facility is constructed. Researchers have addressed the problem by creating three dimensional block layout solutions using different approaches. One of the simplest solutions is to add the height information to the two dimensional block layout, and factor in the height by

extruding the two dimensional blocks along the third dimension to depict the height. Another popular approach includes the third dimension information in the mathematical problem formulation itself, so that the layout solution contains three-dimensional information.

Production planning and control can be subdivided into planning and execution levels and for each level, we have to consider scheduling and capacity. Schedule determines what is to be produced. The equation has to be balanced by considering capacity, which is the consideration of availability of facilities to meet the production level. Table 1.1 shows one method of classifying production planning and control functions.

Table 1.1 The planning and control components.

Schedule	Capacity	Level
Business plan	Financial planning	Planning
Production planning	Resource requirement plan (RRP)	
Master production schedule (MPS)	Rough cut capacity plan (RCCP)	
Material requirement plan	Capacity requirement plan (CRP)	
Final assembly schedule	Capacity control	Execution
Stock picking schedule	Inventory control	
Order priorities	Factory order control	
Scheduling	Machine (work-centre) control	
Operation sequencing	Tool control	
	Preventive maintenance	

Those who are updated with information technology development and decision technology will have great opportunities to help people in decision making and create value for themselves and customers. For other people who are too much behind the development of IT may find themselves to be bothered or even out of business because of information explosion (information overload) and technology obsolete. Competence and confidence are closely related to decision-making. The number of levels in the scenegraph is dictated by the number of levels of logical grouping in the facility model. Each logical group possesses specific behavioral attributes. These can be encapsulated in the corresponding level of the scenegraph structure.

1.1 Experience, learning and memory are the basis for interpreting and judging arriving events.

1.2 The dynamics of unfavorable discrepancies, between the ideal goal states (or

equilibriums) and the perceived states, create the dynamic change of *charge structure*, which commands attention allocation and prompts actions, passively or actively; (the charge, a kind of mental force, is a precursor to drive or stress). A facilities planner requires more information to perform extensive analysis of the facility in terms of operations, such as production planning.

- 1.3 *Dynamic attention allocation*, at any given point in time, to the events perceived as most significant (measured in terms of charges) is a fundamental element in human information processing.
- 1.4 The *least resistance principle*, which is the way that human beings release their charges, includes *active problem solving* or *avoidance justification*.
- 1.5 External information is necessary for human beings to achieve and maintain their ideal goals; unless attention is paid, the external information is not processed.

In this case we have the following expansion of functions $f(x)$ and $v(x)$ at the origin

$$f(x) = f_1 x + \frac{f_3}{6} x^3 + x_6^3, \quad (1.3)$$

the calculations show us that the $f(x)$ function is monotonically decreasing in the value of $f_3 + x^6$. The constrained Eq. (1.3) for the initial data, as $v(x) = 0$ we have the following constraint for $f_1 : |f_1| < 1/\sqrt{2}$. The numerical calculations are presented in Fig. 1.1.

1.2 Theorem Samples

Theorem 1.1 *Let V be a closed complex analytic subvariety of a complex hyperbolic space form of finite volume. Then the Gauss mapping for V is non-degenerate unless $V, (p_i, q_i)$ is totally geodesic. The \mathbf{m} is replaced by \mathbf{n}_+ (\mathbf{n}_+ being the positive part of \mathbf{n}).*

Lemma 1.1 *In $\{P_i\}$ and $M_{\text{rs}}(c\mathfrak{p}, h)$ be a Verma module for \mathfrak{ns} and $w\hat{\mathbf{I}}$ $M_{\text{rs}}(c_{p\mathfrak{q}}, h)$ a singular vector of weight $n + h(n\hat{\mathbf{I}} - \frac{1}{2}\mathbb{N})$. The coefficients $\acute{o}_{\acute{a}, \hat{a}}$ of \acute{o} are independent of the leaf coordinates; namely, $\acute{o}_{\acute{a}, \hat{a}}(u, w) = \acute{o}_{\acute{a}, \hat{a}}(u)$. The intense outbursts of low energy \tilde{a} -rays from neutron stars there has been a lot of interest in the study of NS and their intense magnetic fields.*

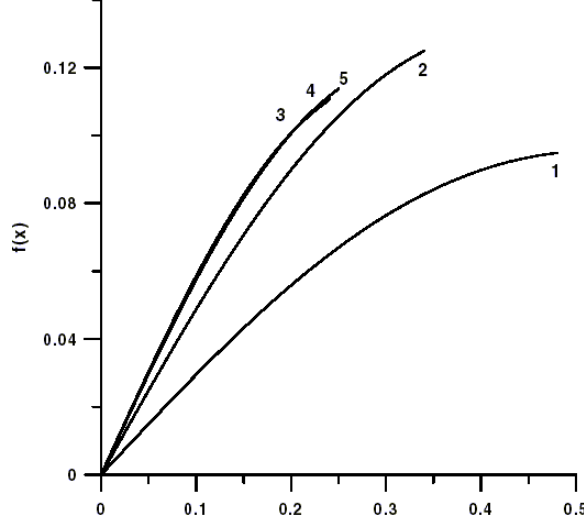


Fig. 1.1 The function $f(z)$. $v_0 = 0.2$; $f_1 = 0.3, 0.5, 0.6, 0.61, 0.615$.

Proposition 1.2 *Let X be a Moishezon variety with 1-rational singularities, that is; X is normal and has a resolution $\mathbf{p} : Y \rightarrow X$ such that $R^1 \mathbf{p}_* Q_y = 0$. Then an analytic homology class $b \in A_2(X, \mathbf{Q})$ is zero if it is numerically equivalent to 0. In particular, $Al_2(X, \mathbf{Q}) = N_1(X)_{\mathbf{Q}}$.*

The processors run in parallel and asynchronously, and they store their intermediate results into a share data area. The input process provides the characters of an input sentence to the system.¹ Each translation processor uses its own information to analyze the source language sentence and generate its translation. The translation system then matches and adjusts the results generated by the different processors automatically. Each processor puts its emphasis on a certain aspect of language analysis, generating its result independently.

2.1.1 Genetic algorithms versus traditional optimization and search techniques

Traditional search methods include such methods as calculus-based methods, and enumerative methods. Calculus methods search for extrema (maxima and

¹ A set of dialogue is divided into sentences. DMTMP produces a sentence by sentence translation of the source language.

minima) by equating the first derivative to zero. Enumerative method uses a finite search space or a discretised infinite search space to consider objective function values at every point in the space one at a time. The limitation of this method is that it is only effective in a small search space. Traditional methods lack robustness because

- (1) they are local in scope and the optima that they seek are the best in a neighborhood of the current point;
- (2) calculus method depends on the existence of derivatives;
- (3) they depend on restrictive requirements of continuity, whilst many practical functions are discontinuous in nature;

The search techniques that cautiously exploits historical information in order to speculate strings with higher potential of better performance, i.e. those approaching the optimal solution. Simply, genetic algorithms reach the solution of a problem by generating and modifying a certain number of tentative solutions so as to find the individual (i.e. the solution) best suited to a given environment (i.e. the problem domain). A solution is represented by a string of numbers or characters forming a so-called string. A set of strings is referred to as a solution space. A random initialization of a population, the algorithm proceeds in an iterative way through:

Appendix A

The Dynamic Optimization

The static neoclassical theory of a firm and its dynamization by dynamic optimization assume profit functions inconsistent with each other. As a solution to this, we present a dynamic theory of a firm which is consistent with the static neoclassical theory. We define the ‘economic forces’ which act upon the production of the firm and show that the adjustment of production in a profit-seeking way may be stable or unstable. Explosive unstable production dynamics may occur due to ‘economies of scale’ or due to the development of wealth or technology; in stable cases the adjustment leads to the profit maximizing situation. Our model provides a micro basis for the modeling of economic growth at macro-level.

In the theory only equilibrium states are studied, and the adjustment process from one equilibrium to another is not modeled. In physics, too, the equilibrium states of various dynamic systems were known much before Newton defined his dynamic laws of mechanics. Static analysis, however, is not in accordance with the observed evolutionary behavior of economies, which requires a dynamic framework for modeling.

Most theories of economic growth concentrate on steady-states. The equilibrium (steady) state of a dynamic system may be a fixed point or a fixed time path. The first law of Newton — A body remains at rest or in a uniform rectilinear motion unless acted upon by a force — covers these both. This implies that in the modeling of economic dynamics, the equilibrium (zero-force) assumption has had a dominating role. Our aim is to extend this tradition by defining the forces which act upon the production of a firm in a non-equilibrium situation, and to show that production dynamics can be modeled analogously with Newtonian mechanics. The neoclassical theory of a firm assumes that firms’ productions in a given time unit are the profit maximizing ones. In real life, however, firms’ demand change continuously and firms adjust their productions on this basis. If we now replace the assumption that firms produce in a profit

maximizing way by assuming that firms like to better their situation if possible, with this principle we can model the adjustment of production so that the modeling covers also possible steady-states as well as changes in demand and costs. We believe that the willingness of economic agents (entrepreneurs, consumers, workers etc.) to better their situation in a competitive environment is the fundamental cause of economic dynamics. The assumption that firms behave in an optimal way prohibits the understanding of production dynamics because no firm likes to change an optimal behavior.

$$P(L) \propto (1 - q)^L. \quad (\text{A.1})$$

Firms like to sell their whole production at a maximum possible unit price, and they know that the unit price is either determined according to demand and supply at the market in the competitive market case, or is set by the firm within the limits that other firms' pricing policies set in the case of monopolistic competition or a monopoly firm. Firms know that they can sell their whole production at a unit price low enough, but unit price under unit costs creates losses. The ambiguousness of the planners of a single firm is thus focused on uncertainty about the maximum unit price the products of the firm can be sold and on unit production costs.

Bibliography

- Amsden, A. A. and Harlow, F. H. (1970). The SMAC method: A numerical technique for calculating incompressible fluid flows, Los Alamos Sci. Lab. Rep. No. LA-4370.
- Aoyama, T. (1988). Study on offshore wave control by a submerged plate, M. Eng. Thesis, Department of Civil Eng., Univ. of Tokyo, 121p. (in Japanese).
- Burke, J. E. (1964). Scattering of surface waves on an infinitely deep fluid, *J. Math. Phys.* , 6, pp. 805–819.
- Hattori, M. (1975). Wave transmission through a submerged plate, *Proc. 22nd Japanese Conf. Coastal Eng.*, JSCE, pp. 513–517 (in Japanese).
- Hattori, M. and Matsumoto, H. (1977). Hydraulic performances of a submerged plate as breakwater, *Proc. 24th Japanese Conf. Coastal Eng.*, JSCE, pp. 266–270 (in Japanese).
- Ijima, T., Ozaki, S., Eguchi, Y. and Kobayashi, A. (1970). Breakwater and quay wall by horizontal plates, *Proc. 12th Conf. Coastal Eng.*, ASCE, pp. 1537–1556.
- Imai, T., Akiyama, Y., Ikeya, T., Kudo, K. and Tsuzuki, S. (1987). Wave focusing by a submerged crescent plate, *Proc. Coastal Eng. JSCE* : 487–491 (in Japanese).
- Kojima, H., Ijima, T. and Yoshida, A. (1992). Decomposition and interception of long waves by a submerged horizontal plate, *Proc. 22nd Conf. Coastal Eng.*, ASCE, pp. 1228–1241.
- Kojima, H., Yoshida, A. and Ijima, T. (1991). Second order interactions between waves and a submerged horizontal plate, *Coastal Eng. in Japan* , 2, pp. 152–172.
- Liu, P. L. F. and Abbaspour, M. (1982). Wave scattering by a rigid thin barrier, *J. Waterway Port Coastal Ocean Eng.*, ASCE , 4, pp. 479–491.
- Liu, P. L. F. and Iskandarani, M. (1991). Scattering of short-wave groups by submerged horizontal plate, *J. Waterway Port Coastal Ocean Eng.*, ASCE , 3, pp. 235–246.
- Martin, P. A. and Farina, L. (1997). Radiation of water-waves by a heaving submerged horizontal disk, *J. Fluid Mech.* , 7, pp. 365–379.
- McIver, M. (1985). Diffraction of water waves, *J. Eng. Math.* , 5, pp. 297–319.
- Parsons, N. F. and Martin, P. A. (1992). Scattering of water waves by submerged plates using hypersingular integral equations, *Appl. Ocean Res.* 14: 313–321.
- Patarapanich, M. (1984). Maximum and zero reflection from submerged plate, *J. Waterway Port Coastal Ocean Eng.*, ASCE , 2, pp. 171–181.
- Patarapanich, M. (1987). Forces and momentum on a horizontal plate due to wave scattering, *Coastal Eng.* , 2, pp. 279–301.
- Patarapanich, M. and Cheong, H. F. (1989). Reflection and transmission characteristics of regular and random waves from a submerged horizontal plate, *Coastal Eng.*, 10, pp. 161–182.

- Siew, P. F. and Hurley, D. G. (1977). Long surface wave incident on a submerged horizontal plate, *J. Fluid Mech.*, 3, pp. 141–151.
- Yip, T. L. and Chwang, A. T. (1997). Water-wave control by a pitching plate, *J. Eng. Mech.*, ASCE, 8, pp. 800–807.
- Yoshida, A., Kojima, H. and Trurumoto, Y. (1990). A collocation method of matched eigenfunction expansions on the boundary-value problem of wave-structure interactions, *Proc. Japan Soc. Civil Eng.*, No. 417, pp. 265–274 (in Japanese).
- Yu, X. (1990). Study on wave transformation over submerged plate, PhD Thesis, University of Tokyo, 151p.
- Yu, X. (1995a). Diffraction of water waves by porous breakwaters, *J. Waterway Port Coastal Ocean Eng.*, ASCE, 6, pp. 275–282.
- Yu, X. (1995b). Patching methods for the analysis of wave motion over a submerged plate, *Rep. Fac. Eng.*, Nagasaki University, 44, pp. 35–42.
- Yu, X. and Chwang, A. T. (1993). Analysis of wave scattering by submerged circular disk, *J. Eng. Mech.*, ASCE, 9, pp. 1804–1917.
- Yu, X. and Chwang, A. T. (1994). Water waves above submerged porous plate, *J. Eng. Mech.*, ASCE, 6, pp. 1270–1282.
- Yu, X. and Dong, Z. (2001). Direct computation of wave motion around submerged plates, *Proc. 29th Cong. Int. Assoc. Hydr. Res.*, in press.
- Yu, X., Isobe, M. and Watanabe, A. (1989). Linear analysis of wave transformation over a submerged plate, *Proc. 44th Ann. Conf. Japan Soc. Civil Eng.*, Part 2, pp. 678–679 (in Japanese).
- Yu, X., Isobe, M. and Watanabe, A. (1990). Numerical simulation of nonlinear wave transformation over a submerged plate, *Proc. 22nd Conf. Coast. Eng.*, ASCE, pp. 136–159.
- Yu, X., Isobe, M., Watanabe, A., Kimura, H. and Sekida, S. (1991a). Semi-empirical formulas of wave reflection and transmission coefficients due to a submerged plate, *Proc. 46th Ann. Conf. Japan Soc. Civil Eng.*, Part 2, pp. 890–891 (in Japanese).
- Yu, X., Isobe, M. and Watanabe, A. (1991b). Reflection and transmission of irregular waves by a submerged plate, *Proc. 46th Ann. Conf. Japan Soc. Civil Eng.*, Part 2, pp. 892–893 (in Japanese).
- Yu, X., Isobe, M., Watanabe, A. and Sakai, K. (1991c). Analysis of wave motion over submerged plate by boundary element method, *Proc. Int. Assoc. BEM Symp.*, Kyoto, pp. 393–419.
- Yu, X., Isobe, M. and Watanabe, A. (1995). Wave breaking over submerged horizontal plate, *J. Waterway Port Coastal Ocean Eng.*, ASCE, 2, pp. 105–113.
- Zhang, S. and Williams A. N. (1996). Wave scattering by an elliptic disk, *Port Coastal Ocean Eng.*, ASCE, 1, pp. 38–68.

Index

ability, 3

chaos, 1

complex, 1

cost, 1

geometric, 2

layout, 2

length, 2

market, 1

mixture, 2

multiple, 1

optimal, 7

orbits, 3

paper, 1

phenomena, 2

plans, 1

products, 1

state, 2

theory, 1

vector, 3

word, 2

workforce, 1